

# Semi-stabilization for the semilinear damped wave equation

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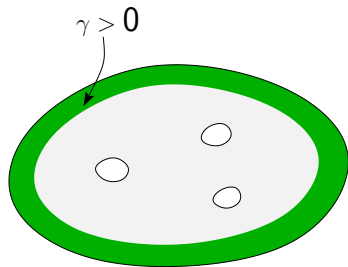
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*Joint work with Camille Laurent, CNRS-Paris VI*

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# The semilinear damped wave equation

$$\partial_{tt}^2 u + \gamma(x) \partial_t u = \Delta u - f(x, u)$$



- $\Omega$  is a smooth compact manifold of dimension  $d = 2$  with Dirichlet boundary conditions.
- the damping  $\gamma$  is in  $\mathbb{L}^\infty(\Omega)$ ,  $\gamma(x) \geq 0$
- $f$  is smooth and of degree  $p$   
 $|f(x, u)| + |f'_x(x, u)| \leq C(1 + |u|)^p$   
 $|f'_u(x, u)| \leq C(1 + |u|)^{p-1}$
- $f$  is asymptotically of the sign of  $u$ :  
 $\forall |u| \geq R, \quad f(x, u)u \geq 0$

$$\partial_{tt}^2 u + \gamma(x)\partial_t u = \Delta u - f(x, u)$$

Set  $X = H_0^1(\Omega) \times L^2(\Omega)$  and

$$U = \begin{pmatrix} u \\ \partial_t u \end{pmatrix} \quad A = \begin{pmatrix} 0 & Id \\ \Delta & -\gamma(x) \end{pmatrix} \quad F(U) = \begin{pmatrix} 0 \\ f(x, u) \end{pmatrix}$$

$\Rightarrow e^{At}$  is a dissipative semigroup on  $X$ .

$\Rightarrow$  Since  $f$  is of degree  $p < \infty$  and  $\Omega$  is of dimension  $d = 2$ ,  
 $F : X \rightarrow X$  is defined and Lipschitz on the bounded sets.

We consider in  $X$  the equation

$$\partial_t U = AU + F(U) \quad U(t=0) = U_0 \in X$$

# The gradient dynamics

Set  $V(x, u) = \int_0^u f(x, \xi) d\xi$ . The energy

$$\mathcal{E}(U) = \int_{\Omega} \frac{1}{2} (|\nabla u|^2 + |\partial_t u|^2) + V(x, u) dx$$

is non-increasing along the trajectories since

$$\partial_t \mathcal{E}(U(t)) = - \int_{\Omega} \gamma(x) |\partial_t u|^2 dx$$

$\Rightarrow$  **Global existence of solutions**

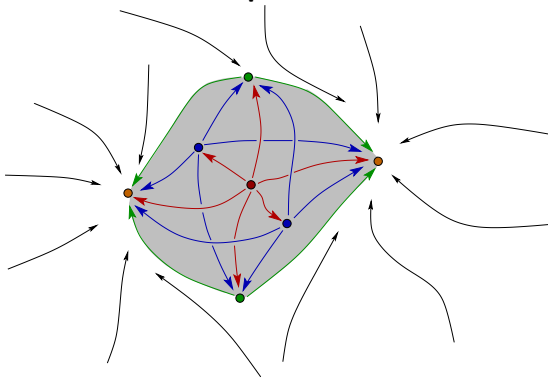
# Motivations

The linear equation is **dissipative** and any solution goes to zero

$$\|e^{At}U\|_X \xrightarrow{t \rightarrow +\infty} 0.$$

**Do we still have stabilization of the nonlinear problem?**

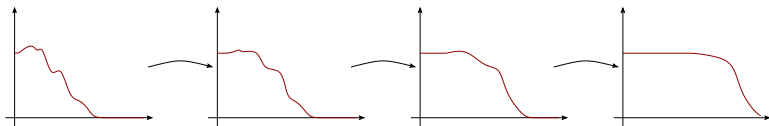
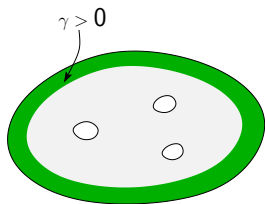
We expect **gradient-like dynamics** in  $X$ : there exists a **compact global attractor** and any trajectory converges to the set of **equilibrium points**.



# Motivations

Related problems:

- Control and stabilization problems.
- Does a linear dissipative (dispersive?) behaviour remains after addition of a nonlinearity?
- Convergence to equilibria/travelling fronts in nonlinear PDEs



# A historic result

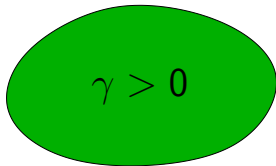
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## A historic result

$$\partial_{tt}^2 u + \gamma(x) \partial_t u = \Delta u - f(x, u)$$

Assume:

- $\gamma(x) \geq \alpha > 0$  in  $\Omega$
- $f$  is of degree  $p < \infty$
- $f$  is asymptotically of the sign of  $u$



Theorem – J.K. Hale (1985) and A. Haraux (1985)

*With the above assumptions, the dynamics of the damped wave equation admit a **compact global attractor**  $\mathcal{A}$ . Moreover, it is gradient-like and **any trajectory converges to the sets of equilibrium points.***



# A historic result

Step 1: the trajectories are bounded.

If  $f$  is asymptotically of the sign of  $u$  and of degree  $p$ , then **the energy is well defined and bounded on bounded sets.**

$$\frac{1}{2} \|U\|_X^2 + \min V \leq \int_{\Omega} \frac{1}{2} (|\nabla u|^2 + |\partial_t u|^2) + V(x, u) \, dx \leq K(\|U\|_X).$$

Since  $\mathcal{E}$  is non-increasing, **the trajectories of bounded sets are bounded.**

# A historic result

Step 2: the asymptotic compactness.

The linear semigroup is stabilized:

$$\forall t \geq 0, \quad \|e^{At}\|_{\mathcal{L}(X)} \leq Me^{-\lambda t}$$

Moreover, if  $f$  is of degree  $p$ , then

$F : \begin{pmatrix} u \\ v \end{pmatrix} \in H_0^1(\Omega) \times L^2(\Omega) \mapsto \begin{pmatrix} 0 \\ f(x, u) \end{pmatrix} \in H_0^1(\Omega) \times L^2(\Omega)$  is compact.

$$U(t) = e^{At}U_0 + \int_0^t e^{A(t-s)}F(U(s)) \, ds$$

$\Rightarrow$  **the bounded sets admits compact  $\omega$ -limit sets.**

# A historic result

Step 3: a unique continuation property.

It is sufficient to show that the  $\omega$ -limit sets consists of equilibrium points. By Lasalle's principle, the trajectories  $U(t) = (u, \partial_t u)$  in the  $\omega$ -limit sets have constant energy. So we have

$$\partial_t \mathcal{E}(U(t)) = - \int_{\Omega} \gamma(x) |\partial_t u|^2 dx = 0 .$$

Since  $\gamma(x) \geq \alpha > 0$ , we have  $\partial_t u \equiv 0$  and thus  $u$  is an equilibrium point.

# A historic result

- Asymptotic compactness  $\Leftrightarrow$  high frequencies are not really modified by the nonlinearity
- Unique continuation  $\Leftrightarrow$  classify low-frequency solutions (equilibria, travelling fronts. . .)

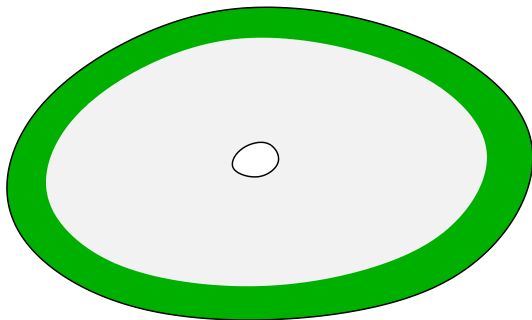
## Key arguments where we use $\gamma$ positive:

- 1  $\|e^{At}\|_{\mathcal{L}(X)} \leq Me^{-\lambda t}$  has finite integral on  $[0, +\infty)$
- 2 if  $\mathcal{E}(U(t))$  is constant, then  $\int \gamma(x)|u_t|^2 = 0$  and  $u(t)$  is constant.

# A standard extension

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What happens when  $\gamma(x)$  may vanish?



# The decay of the linear semigroup

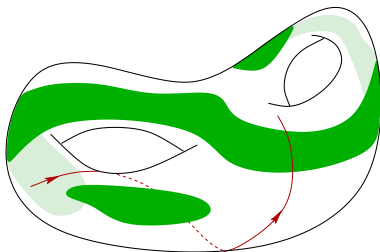
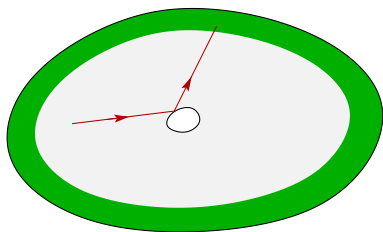
Theorem – J. Rauch and M. Taylor (1974)

C. Bardos, G. Lebeau and J. Rauch (1992)

$$\|e^{At}\|_{\mathcal{L}(X)} \leq Me^{-\lambda t}$$



*Any long enough geodesic meets the support of the damping  $\gamma$*



# The unique continuation property

If  $U(t)$  belongs to an  $\omega$ -limit set,

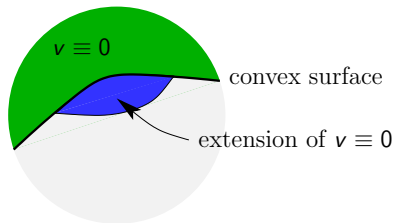
$$\partial_t \mathcal{E}(U(t)) = - \int_{\Omega} \gamma(x) |\partial_t u|^2 dx = 0 .$$

So  $v(t) = \partial_t u(t)$  vanishes in  $\omega$  the support of  $\gamma$ . Thus, we have

$$v \equiv 0 \text{ in } \omega \times \mathbb{R} \quad \text{and} \quad \partial_{tt}^2 v = \Delta v - f'_u(x, u(x, t))v .$$

To conclude that  $v \equiv 0$  everywhere, we need to use a unique continuation property.

Basically, we may extend the zone where  $v \equiv 0$  through **convex surfaces**.

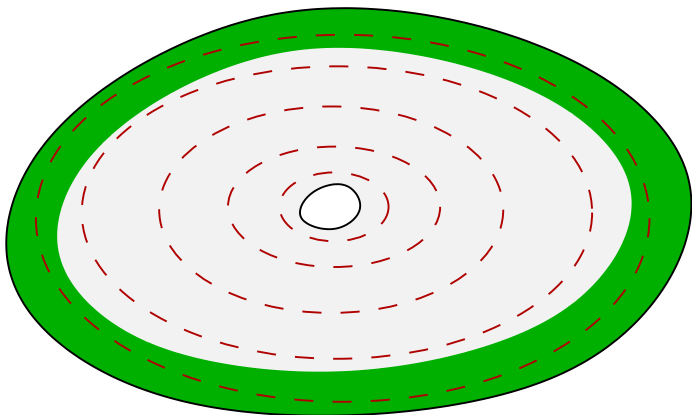


[N. Lerner and L. Robbiano, 1985], [L. Hörmander, 1985], [Tataru, 1996]



# The unique continuation property

The gradient dynamics hold for the domain with zero or one hole

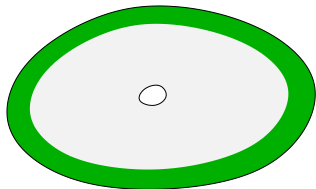


## A classic result

$$\partial_{tt}^2 u + \gamma(x) \partial_t u = \Delta u - f(x, u)$$

Assume:

- $\Omega$  is a two dimensional convex compact domain with or without a convex hole
- $\gamma(x) \geq \alpha > 0$  in a neighborhood of the exterior boundary of  $\Omega$ .
- $f$  of degree  $p$
- $f$  is asymptotically of the sign of  $u$



### Theorem

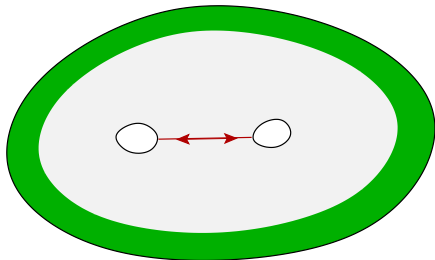
*With the above assumptions, the dynamics of the damped wave equation admit a **compact global attractor**  $\mathcal{A}$ . Moreover, it is gradient-like and **any trajectory converges to the sets of equilibrium points.***

# The disk with two holes

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## Without the geometric control condition

In some cases, the geometric control condition does not hold, but very few geodesics miss the support of the damping.



$$\|e^{At} U_0\|_{H^1 \times L^2} \leq M e^{-\lambda \sqrt[3]{t}} \|U_0\|_{H^2 \times H^1}$$

[N. Burq, 1993]

[N. Burq and M. Zworski, 2004]

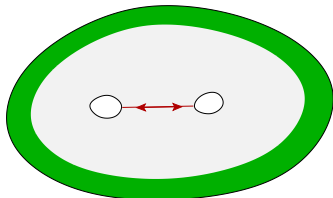
[R.J. and C. Laurent, 2018]

# The disk with two holes

$$\partial_{tt}^2 u + \gamma(x) \partial_t u = \Delta u - f(x, u)$$

Assume:

- $\Omega$  is a convex compact domain of dimension 2 with two convex holes
- $\gamma(x) \geq \alpha > 0$  in a neighborhood of the exterior boundary of  $\Omega$ .
- $f$  of degree  $p < \infty$
- $f$  is asymptotically of the sign of  $u$



Theorem – R.J. and C. Laurent (2018)

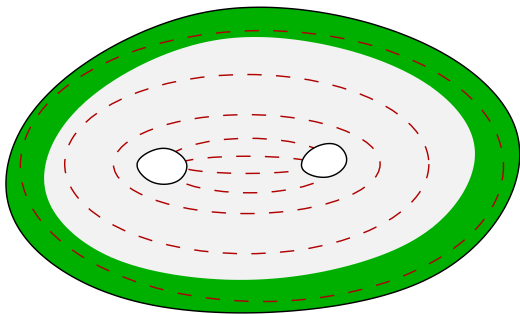
*With the above assumptions, the dynamics of the damped wave equation are gradient-like. Moreover, they admit a **compact global**  $(D(A), X)$ -**attractor**  $\mathcal{A}$  in the following sense: any bounded set of  $D(A) = (H^2 \cap H_0^1) \times H_0^1$  is attracted by  $\mathcal{A}$  in the norm  $X = H_0^1 \times L^2$ . Moreover, **any trajectory converges to the sets of equilibrium points** and the convergence is uniform in balls of  $D(A)$ .*

# The disk with two holes

Main arguments:

$$\|e^{At} U_0\|_{H^1 \times L^2} \leq M e^{-\lambda t^{1/3}} \|U_0\|_{H^2 \times H^1}$$

$$U(t) = e^{At} U_0 + \int_0^t e^{A(t-s)} F(U(s)) ds$$



+ some technical tricks

# The disk with three holes

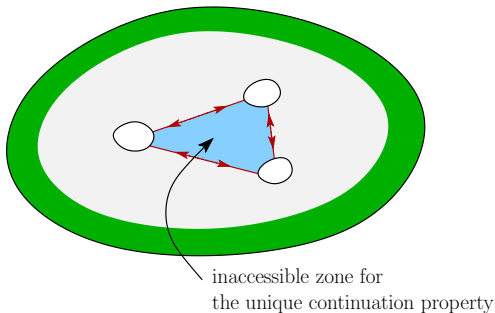
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# The disk with three holes

If there are three holes or more, with additional technical assumptions, we still have the decay

$$\|e^{At}U_0\|_{H^1 \times L^2} \leq Me^{-\lambda \sqrt[3]{t}} \|U_0\|_{H^2 \times H^1}$$

But the unique continuation property of Lerner-Robbiano-Hörmander-Tataru cannot be used:





# An analytic unique continuation property

Theorem – L. Robbiano and C. Zuily (1998) L. Hörmander (1997)

Assume  $\omega \neq \emptyset$  and  $v(t) = \partial_t u(t)$  solves

$$v \equiv 0 \text{ in } \omega \times \mathbb{R} \quad \text{and} \quad \partial_{tt}^2 v = \Delta v - f'_u(x, u(x, t))v .$$

Assume moreover that  $t \mapsto f'_u(x, u(x, t))$  is analytic then  $v \equiv 0$  everywhere.

[J.K. Hale and G. Raugel, 2003] let us hope that if  $f(x, u)$  is analytic in  $u$ , then a function  $u$  in the attractor should be analytic in time and thus  $f'_u(x, u(x, t))$  is also analytic.

# An analytic unique continuation property

In the proofs of [J.K. Hale and G. Raugel, 2003], a global solution  $u$  is split between the **low-frequencies**  $P_n u$  and the **high-frequencies**  $Q_n u$ . It is used that

$$\|e^{At}U\|_X \leq Me^{-\lambda t}\|U\|_X \implies \|e^{Q_n A Q_n t} Q_n U\|_X \leq Ne^{-\mu t}\|Q_n U\|_X .$$

In our case, we would like to obtain

$$\|e^{At}U\|_X \leq Me^{-\lambda \sqrt[3]{t}}\|U\|_{D(A)} \implies \|e^{Q_n A Q_n t} Q_n U\|_X \leq h(t)\|Q_n U\|_{D(A)} .$$

$\implies$  we adapt the ideas of [J.K. Hale and G. Raugel, 2003] but several technical problems have to be overcome.

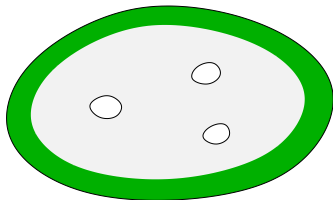
[C.J.K. Batty and Th. Duyckaerts, 2008], [A. Borichev and Y. Tomilov, 2010],  
[N. Anantharaman and M. Léautaud, 2014]

# The disk with three holes

$$\partial_{tt}^2 u + \gamma(x) \partial_t u = \Delta u - f(x, u)$$

Assume:

- $\Omega$  is as opposite and the holes are not aligned and small enough
- $f(x, u)$  is analytic in  $u$
- $f$  of degree  $p < \infty$
- $f$  is asymptotically of the sign of  $u$



Theorem – R.J. and C. Laurent (2018)

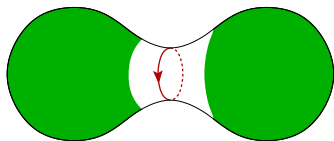
With the above assumptions, the dynamics admit a *compact global*  $(D(A), X)$ -*attractor*. Moreover, **any trajectory converges to the sets of equilibrium points** and the convergence is uniform in balls of  $D(A)$ .

# Conclusion

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- Other geometries are possible

## The peanut of rotation

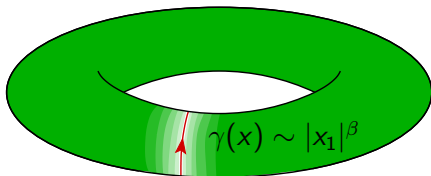


$$\|e^{At}U_0\|_{H^1 \times L^2} \leq Me^{-\lambda\sqrt{t}} \|U_0\|_{H^2 \times H^1}$$

[E. Schenck, 2011]

[H. Christianson, E. Schenck, A. Vasy and J. Wunsch, 2014]

## The torus with degenerated damping



$$\|e^{At}U_0\|_{H^1 \times L^2} \leq \frac{C}{(1+t)^{1+2/\beta}} \|U_0\|_{H^2 \times H^1}$$

[M. Léautaud and N. Lerner, 2015]

- Higher dimension

In dimension  $d = 3$ , assume that  $f$  is Sobolev-subcritical, that is of degree  $p$  with  $p < 3$ . It should also be possible to go to  $f$  energy-subcritical, that is of degree  $p$  with  $p < 5$  by using Strichartz estimates, see [B. Dehman, G. Lebeau and E. Zuazua, 2003], [R.J. and C. Laurent, 2013]

$$U(t) = e^{At} U_0 + \int_0^t e^{A(t-s)} F(U(s)) ds$$

**Open question n.1:**

**How important is the integrability of the linear decay?**

For example, if the linear decay is simply

$$\|e^{At} U_0\|_{H^1 \times L^2} \leq \frac{C}{\ln(2+t)} \|U_0\|_{H^2 \times H^1}$$

does the asymptotic compactness hold?

## Open question n.2:

**In dispersive equations or if  $F$  not compact, can we use appropriate estimates to adapt the proofs?**

## Thanks for your attention!

- R.J. and C. Laurent, *Semi-uniform decay for some semilinear damped wave equations*, almost preprint.
- R.J. and C. Laurent, *A note on the global controllability of the semilinear wave equation*, SIAM Journal on Control and Optimization n°52 (2014), pp. 439–450.
- R.J. and C. Laurent, *Stabilization for the semilinear wave equation with geometric control condition*, Analysis and PDE n°6 (2013), pp. 1089–1119.